

# Finite Element Analysis of Sandwich T-Joints Subjected to Water Slamming Loads

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#### Abstract

This project evaluates the structural response of a sandwich ship hull with Tjoint longitudinal stiffeners subjected to water slamming. Finite element analysis was conducted using the commercial code LS-DYNA. The T-joint stiffeners were modeled as linear elastic springs allowing the vertical displacement and rotation at the panel ends. Three different stiffnesses and two impact velocities were considered. Results were compared to a fixedsupported panel case and showed to be significantly different.

### Introduction

Sandwich composite structures are widely used in marine and aerospace industries due to their high flexural stiffness and low weight properties. Particularly, sandwich panels are currently being implemented in the fabrication of hull structures for lightweight high-speed marine crafts. Typically, sandwich composite panels consist of two thin and stiff face skins bonded to both sides of a thick and lightweight core by an adhesive material. To improve transverse strength, these panels are supported by longitudinal stiffeners. The most common configuration of perpendicular longitudinal stiffeners for sandwich structures is the T-joint [1], shown in Figure 1. When sandwich panels are subjected to flexural loadings, as in the case of water slamming, it is assumed that the face skins carry all the tensile stress whereas the core material carries the shear stress [2].

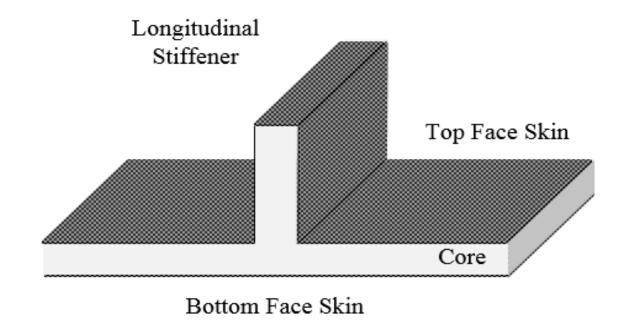


Figure 1. Detail of sandwich T-joint longitudinal stiffener.

Variable slamming conditions induce high-rate fluctuating stresses in the panel constituents, which eventually cause fatigue failure of the structure. The predominant mode of failure of sandwich panels under cyclic flexural loading is core shear, in some cases skin tensile failure has also been observed [3-8]. Consequently, the evaluation of the structural response of sandwich panels with T-joint supports subjected to water slamming is critical for the design of light-weight marine vehicles.

# Background

The classical approach used to study the hull-water slamming problem is the two-dimensional water entry model depicted in Figure 2.

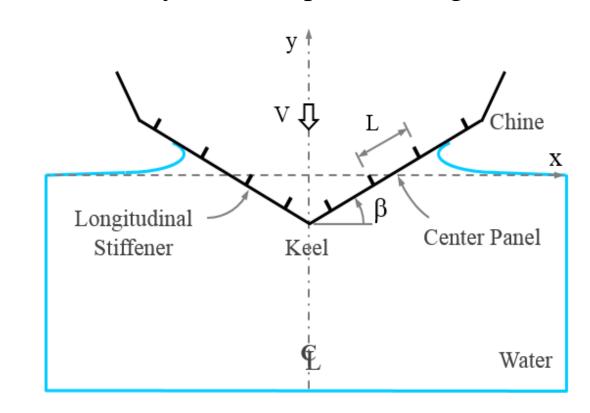


Figure 2. Schematic water slamming on ship hull.

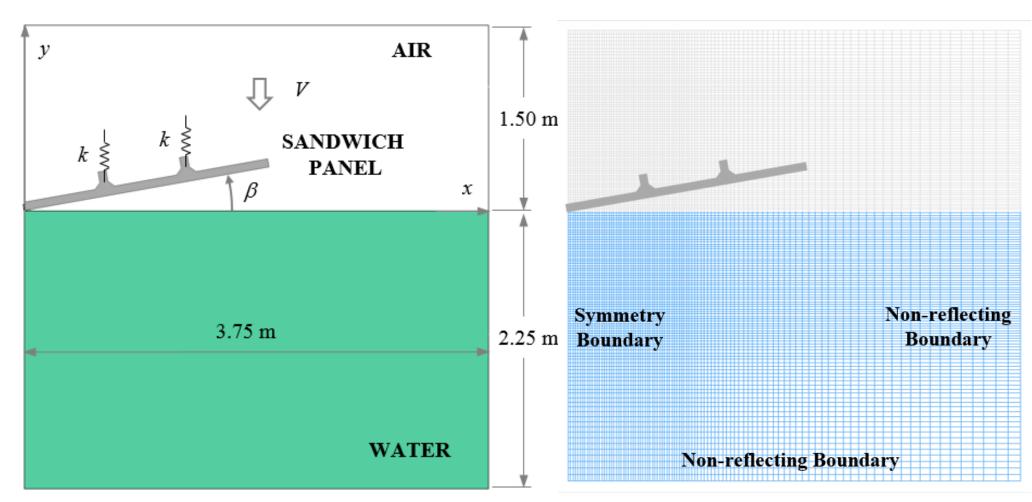
In this model, an elastic hull structure hits an initially calm water surface with constant vertical velocity V [9]. The angle of incidence between the undeformed structure and the undisturbed water surface is referred to as the deadrise angle β. Longitudinal supports are commonly assumed rigid which prevents the local vertical displacement and rotation of the panel ends. This causes high magnitude and high rate shear stresses in the core near the panel supports.

#### **Problem**

The objective of this research is to determine how the stiffness of longitudinal supports affects the magnitude and rate of core shear stresses. For this, finite element (FE) models were developed using the commercial explicit code LS-DYNA, which is well suited for dynamic simulations of fluid-structure interaction (FSI) problems [10–14].

# Methodology

The two-dimensional hull-water slamming problem was modeled using the commercial FE software LS-DYNA. The model consisted of two fluid domains, water and air, and a sandwich composite panel oriented at a particular deadrise angle  $\beta$  with impact velocity V, as shown in Figure 3. Due to the symmetry of the problem along the centerline (see Figure 1), only one half of the hull geometry was modeled. Water and air domains are modeled using an Eulerian mesh (fixed in space), with solid one point (Gauss quadrature integration) Arbitrary-Lagrangian Eulerian (ALE) multi-material elements (ELFORM 11). ALE multi-material formulation allows water material to flow through the air mesh during impact. The sandwich panels and the T-joint supports were modeled using a Lagrangian mesh (attached to the panel) with shell elements for both face skins (ELFORM 2) and fully integrated quadratic solid elements for the core (ELFORM 3). The translational stiffness of the T-joints were modeled using linear springs of stiffness k. The rotation of the T-joints was not restricted. The keel and chine boundary conditions were fixed. The interaction between fluid and structure was managed by the penalty coupling algorithm [15]. The materials for the sandwich constituents were selected based on data reported in the literature [16–18]. The face skins were assumed to be made of orthotropic carbonfiber/epoxy-resin fabric with a lay-up sequence of [0/90]. AIREX C70.130 cross-linked foam was used for both the core material and the T-joint stiffeners.



**Figure 3.** LS-DYNA finite element model. **Figure 4.** FE mesh and boundary conditions.

The mesh extent in z-direction was one element. The analysis was restricted to the x-y plane by constraining all nodes in the z-direction. Symmetry boundary conditions were applied to the water domain along the y-axis (Figure 4). Non-reflecting boundary conditions were defined along the other boundaries of the model simulating a semi-infinite fluid domain. Furthermore, the sandwich hull was modeled using three equal panels of length 0.5 m connected with T-joint supports (see Figure 5). This approach was implemented to isolate the structural response of the central panel from any boundary effect, emulating the conditions of a typical panel in the hull structure. Numerical pressure sensors were placed along the center panel to measure the slamming pressure during the simulation.

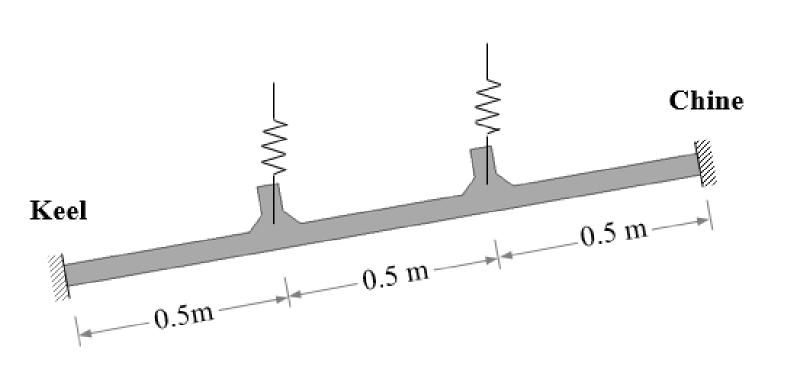


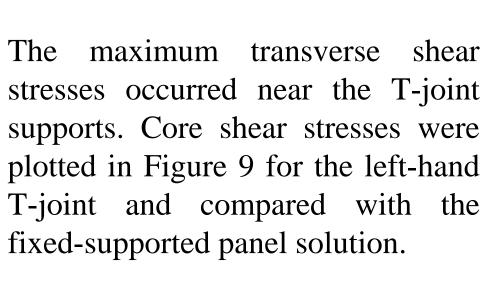
Figure 5. Boundary conditions for sandwich panels.

#### **Results and Discussion**

FE simulations were conducted for three different T-joint stiffnesses and two impact velocities. The angle was maintained each slamming condition the slamming pressure and the structural response of the center was studied. Slamming distribution along the center panel for V = 5 m/s shown in Figure 6. It can be noticed that the effect of increasing the T-joint stiffness affect the magnitude of the pressure peak.

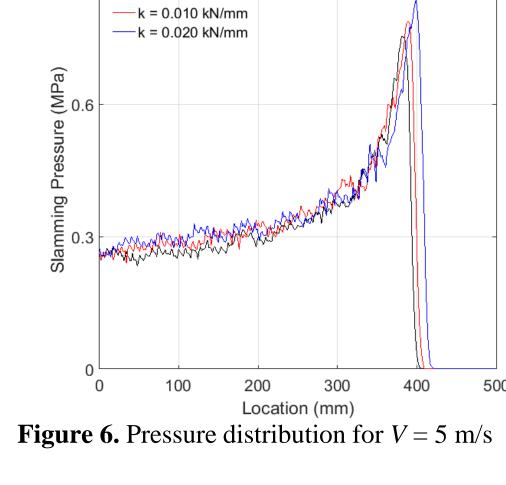
In order to evaluate the stiffness of the T-joint supports, the vertical displacement was plotted, as shown in Figure 7. The maximum displacements occurred at the righthand T-joint. The magnitude of the maximum support displacement is clearly a function of the stiffness k. In all cases, the right-hand T-joint displacement is 50% higher than that of the left-hand T-joint.

mid-span panel deflection was also plotted for the three stiffness cases and compared with the mid-span deflection of the fixed-supported panel (Figure 8). The fixed-supported solution was the result of a previous work [21] The increment in maximum middeflection was directly associated with the displacement of the left-hand T-joint support.

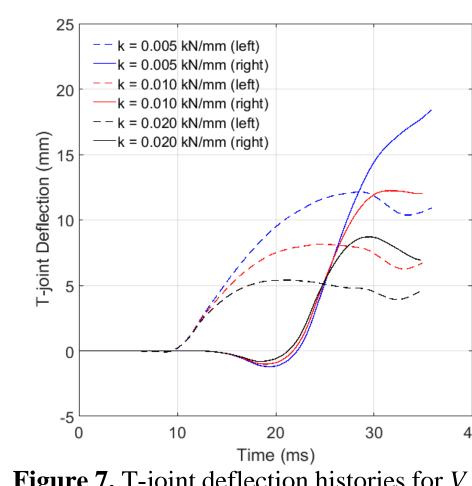


Similarly, core shear stresses at the right-hand T-joint are shown in Figure 10. A significant reduction in maximum core shear stress can be observed in all cases. Additionally, a slight increase in stress rates can be noticed at the left-hand support for both impact velocities. On the other hand, the stress rates at the righthand support remained relatively the same as that in the fixed-supported

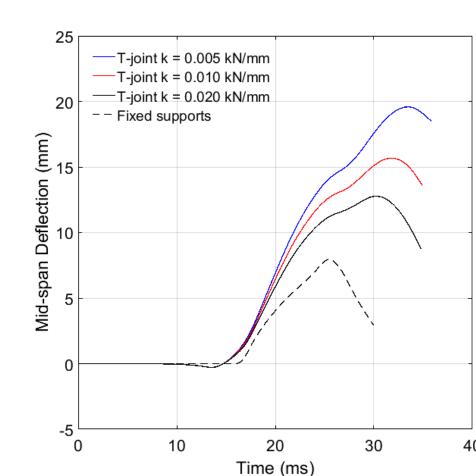
sandwich panel.



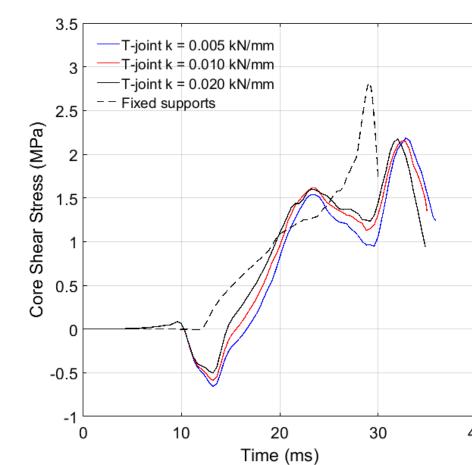
----k = 0.005 kN/mm



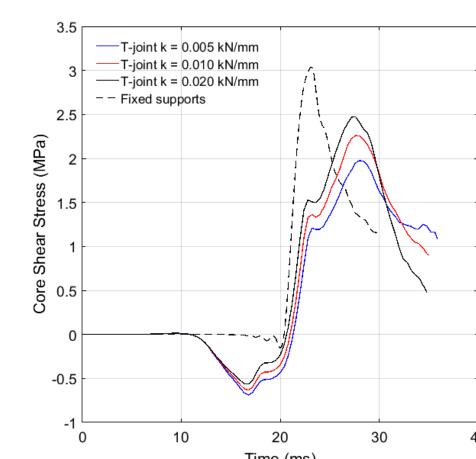
**Figure 7.** T-joint deflection histories for V =5 m/s.



**Figure 8.** Mid-span deflection for V = 5 m/s.



**Figure 9.** Core shear stress for V = 5 m/s (left T-joint)



Time (ms) **Figure 10.** Core shear stress for V = 5 m/s (right T-joint)

# Conclusions

FE analysis showed a strong relationship between the T-joint stiffness and the structural response of the panel. In particular the mid-span deflection was shown to significantly decrease when the T-joint stiffness was increased or when the impact velocity was decreased. On the other hand, core shear stresses increased when higher stiffness or impact velocities were used. Out of all the cases analyzed in this work only the case with conditions  $\beta = 10^{\circ}$ , V = 5 m/s and a stiffness of 0.020 generated core shear failure near the T-joint stiffeners. A good correlation was achieved between the numerical results and experimental data available for elastic and rigid sandwich panels.

#### **Future Work**

The model was only simulated under a small range of slamming conditions. Since these simulations we're performed using the worst case conditions, this opens the door to a wide range of alternate cases that can simulated. Among these are cases where we further increase or decrease the stiffness outside of the ranges used, slower velocities and incrementing the deadrise angle

### Acknowledgements

I would like to thank my mentor Andres Cecchini for all his guidance and patience during this project, as well as the Mechanical Engineering Department and the Graduate School Office at Polytechnic University of Puerto Rico for their support to this work.

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